

# Stage-IV Cosmic Shear and the Curse of Covariate Shift

Cosmology from Home, 2022

Angus H Wright, 24.06.22



GERMAN CENTRE FOR COSMOLOGICAL LENSING



European Research Council

Established by the European Commission

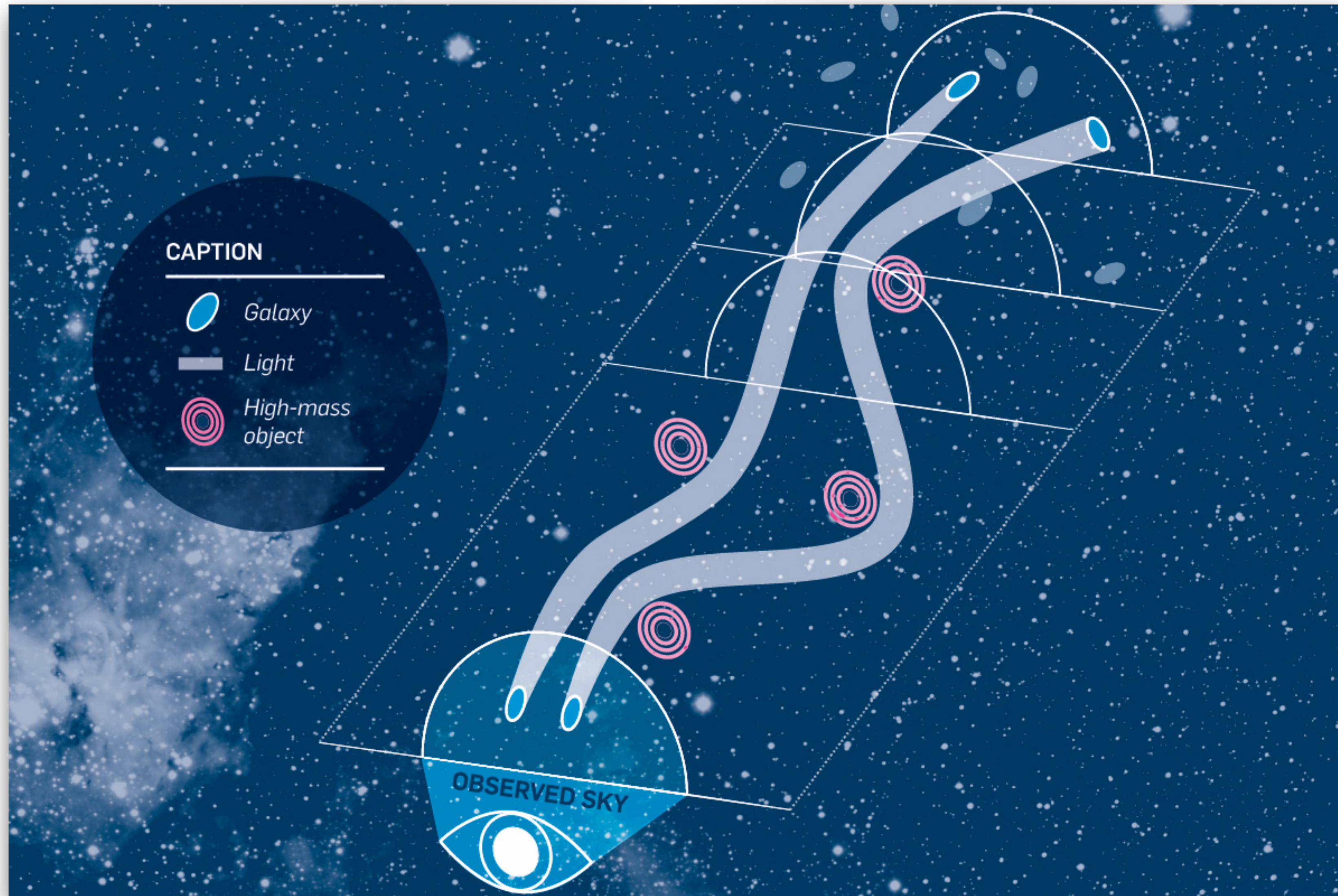
# A brief reminder of cosmic shear



# Fundamentals of Cosmic Shear

3

## Lensing by large-scale structures



Galaxies in the distant universe have (mostly) randomly distributed shapes

Light is distorted along the line-of-sight by massive structures

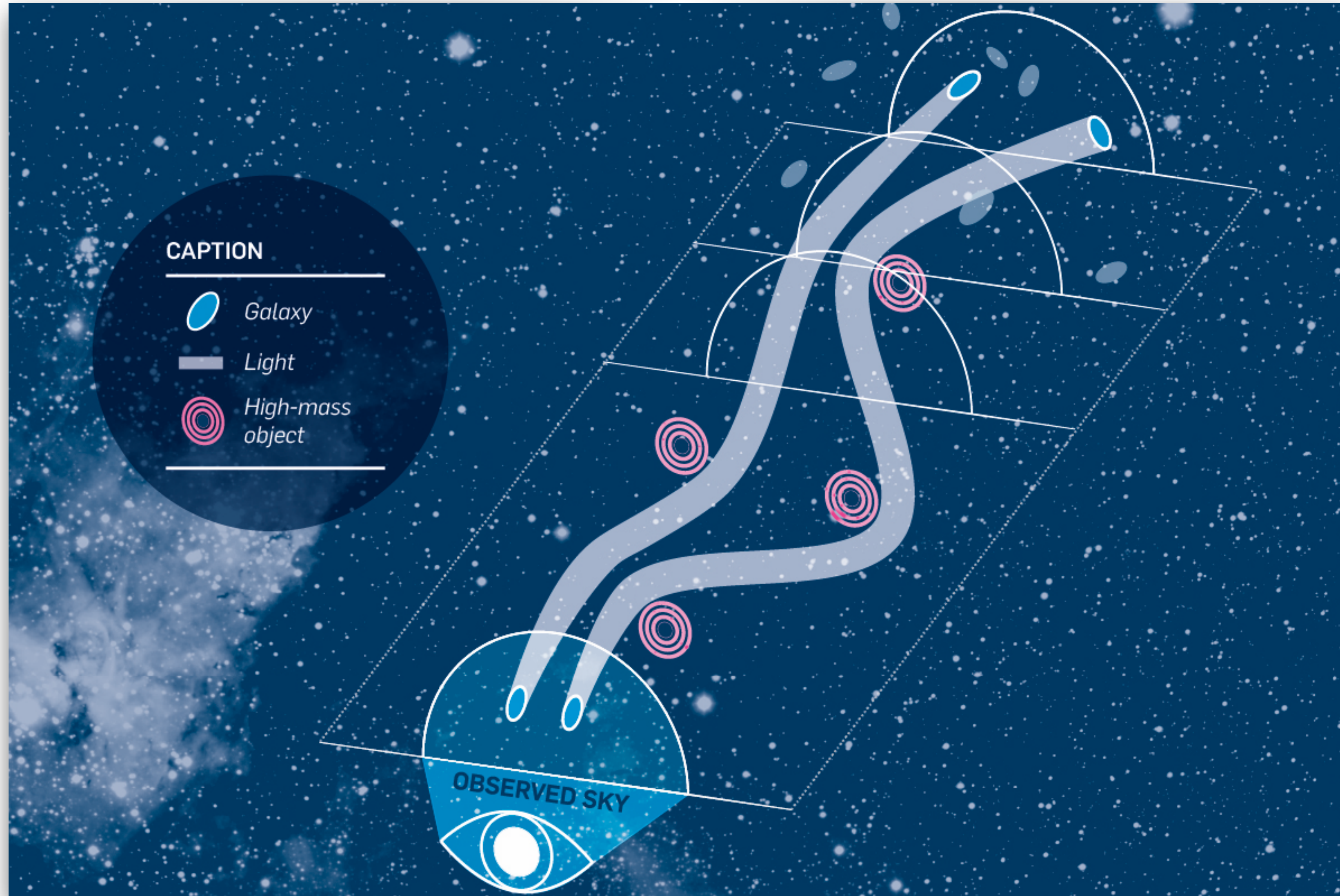
Propagation through similar structures imprints coherent distortions on galaxy shapes



# Robust Cosmic Shear Requirements

4

What do you need to get right?



Shape Measurements

Source Redshift  
Distributions

Modelling of the Source  
galaxy population

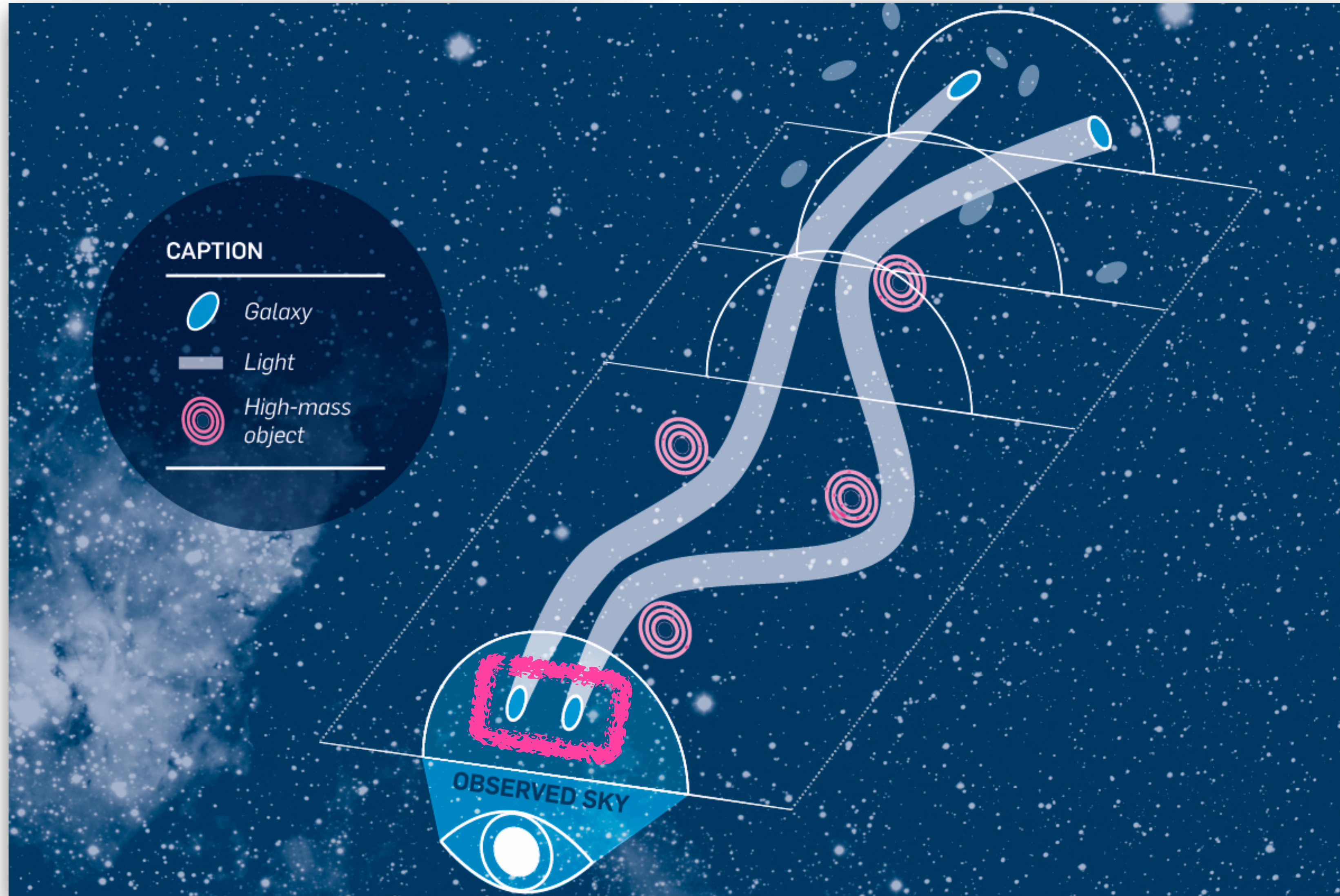
Modelling of baryonic  
effects



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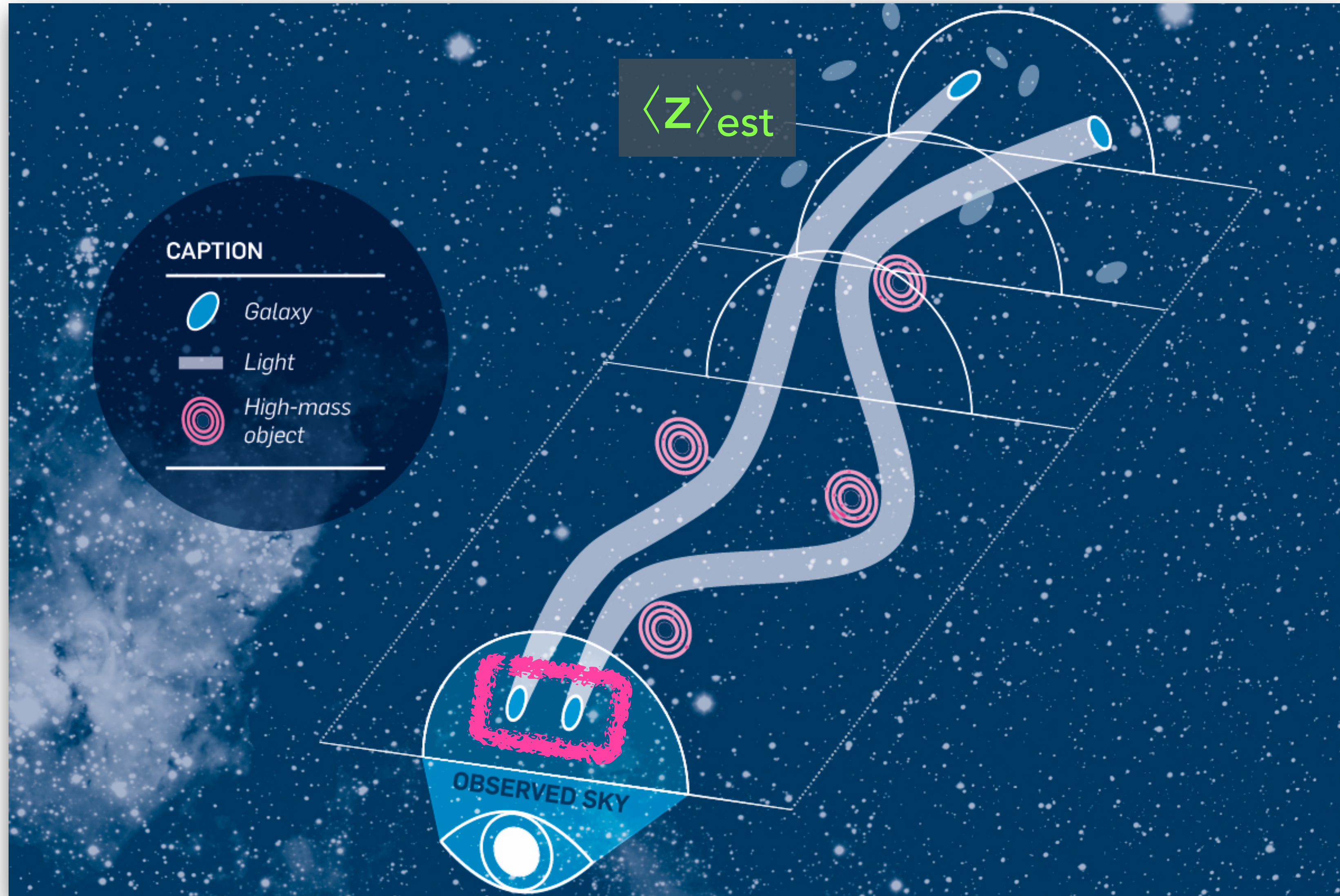
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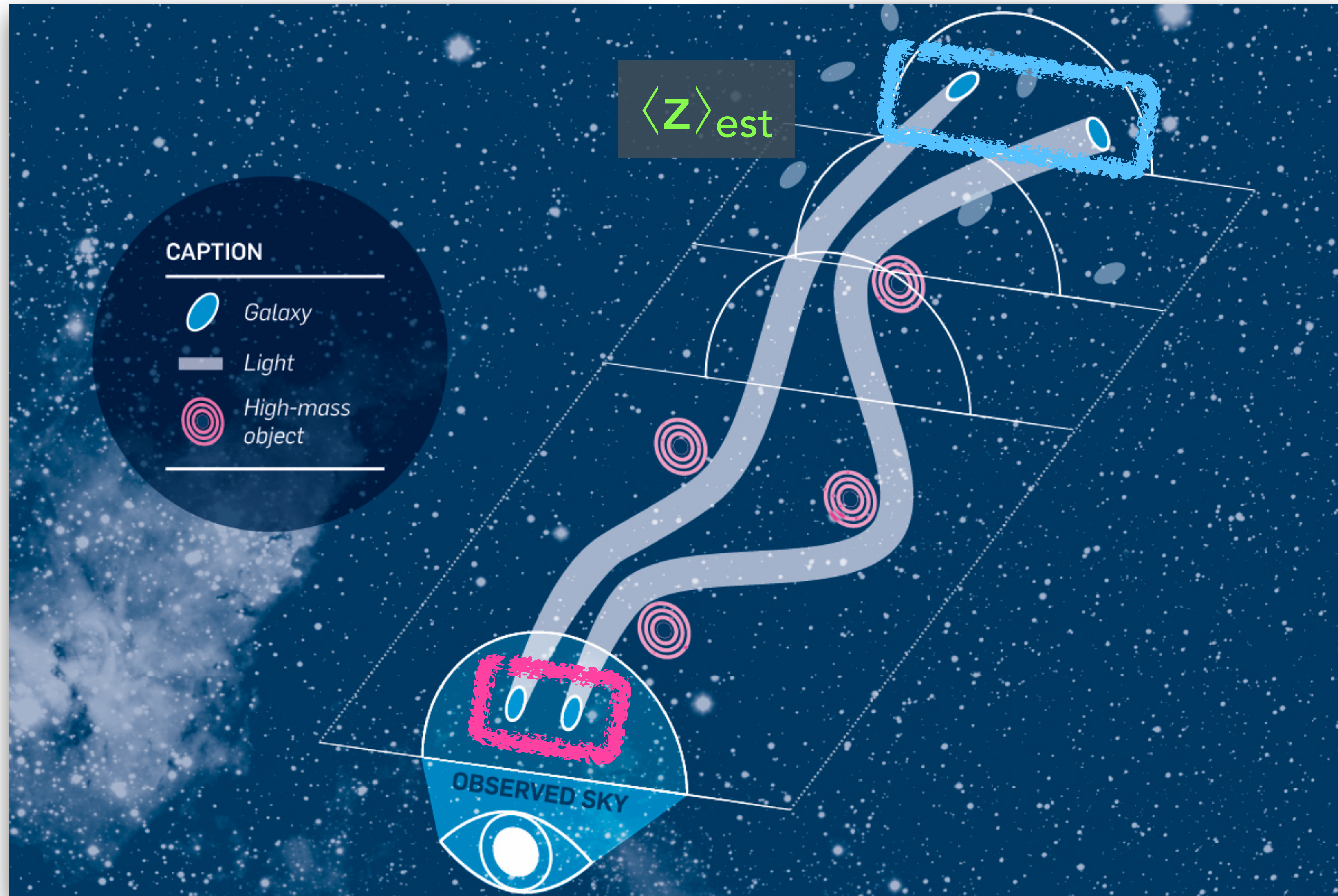
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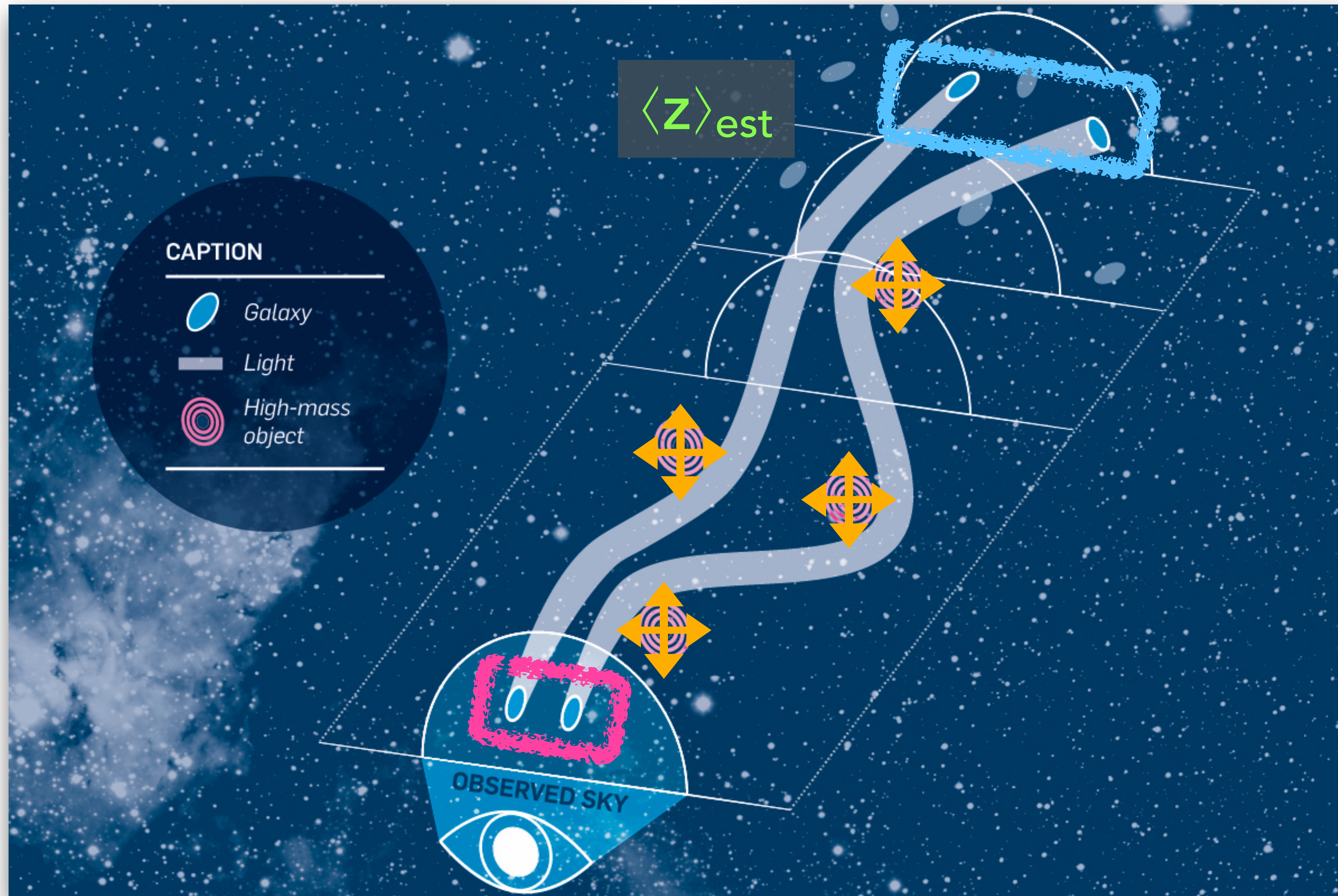
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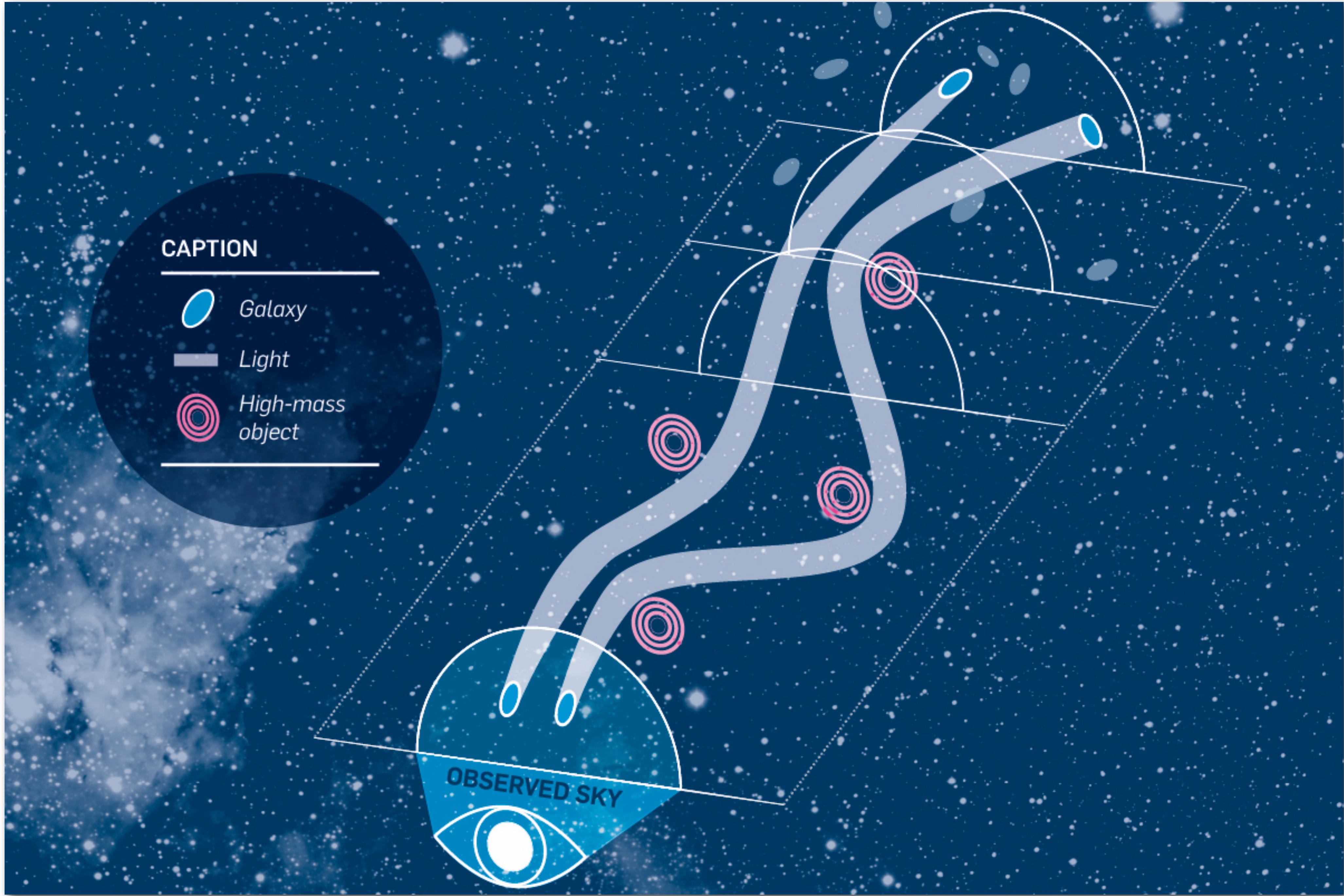
Modelling of the Source  
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Modelling of baryonic  
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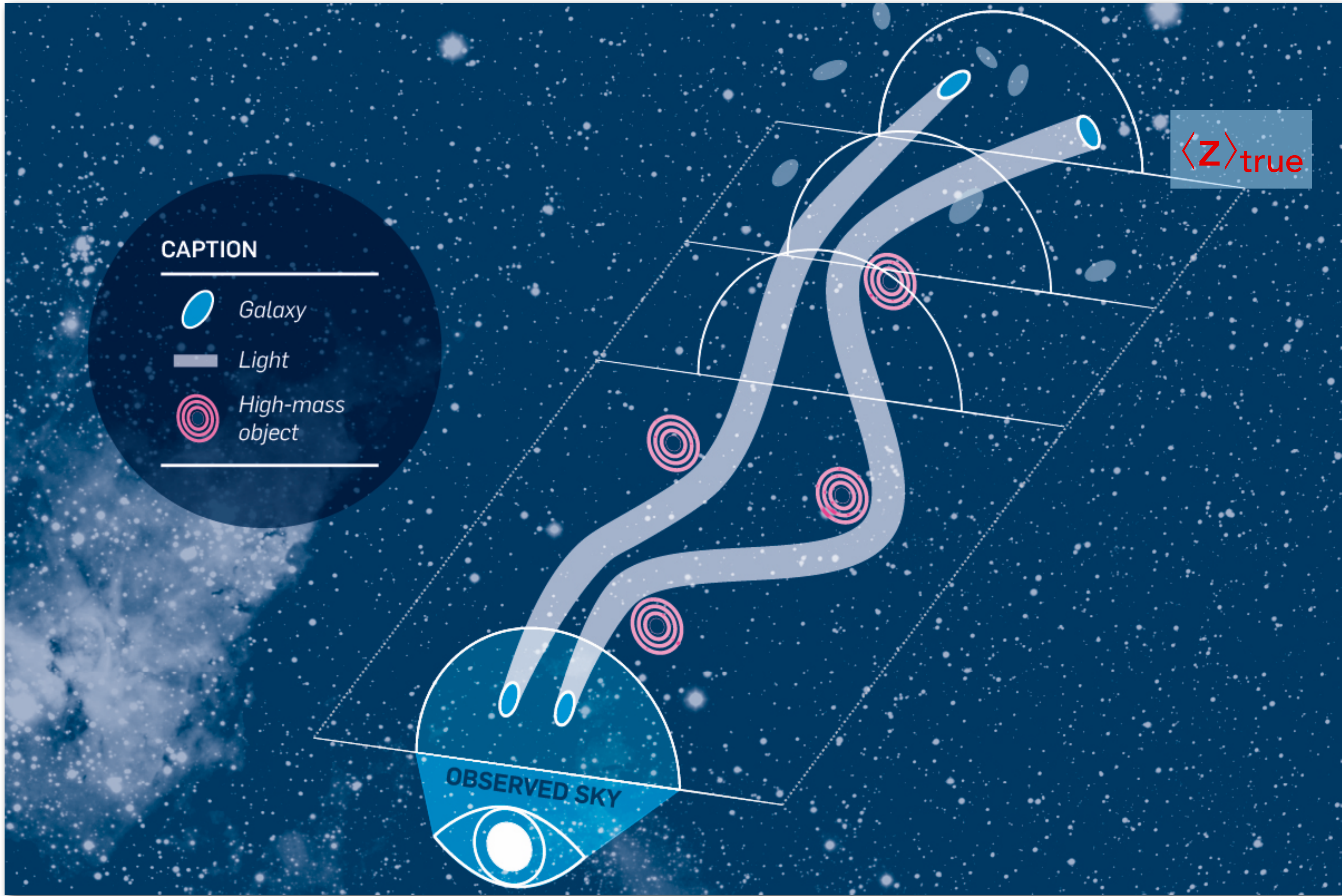


**Why is redshift calibration  
important for cosmic shear?**

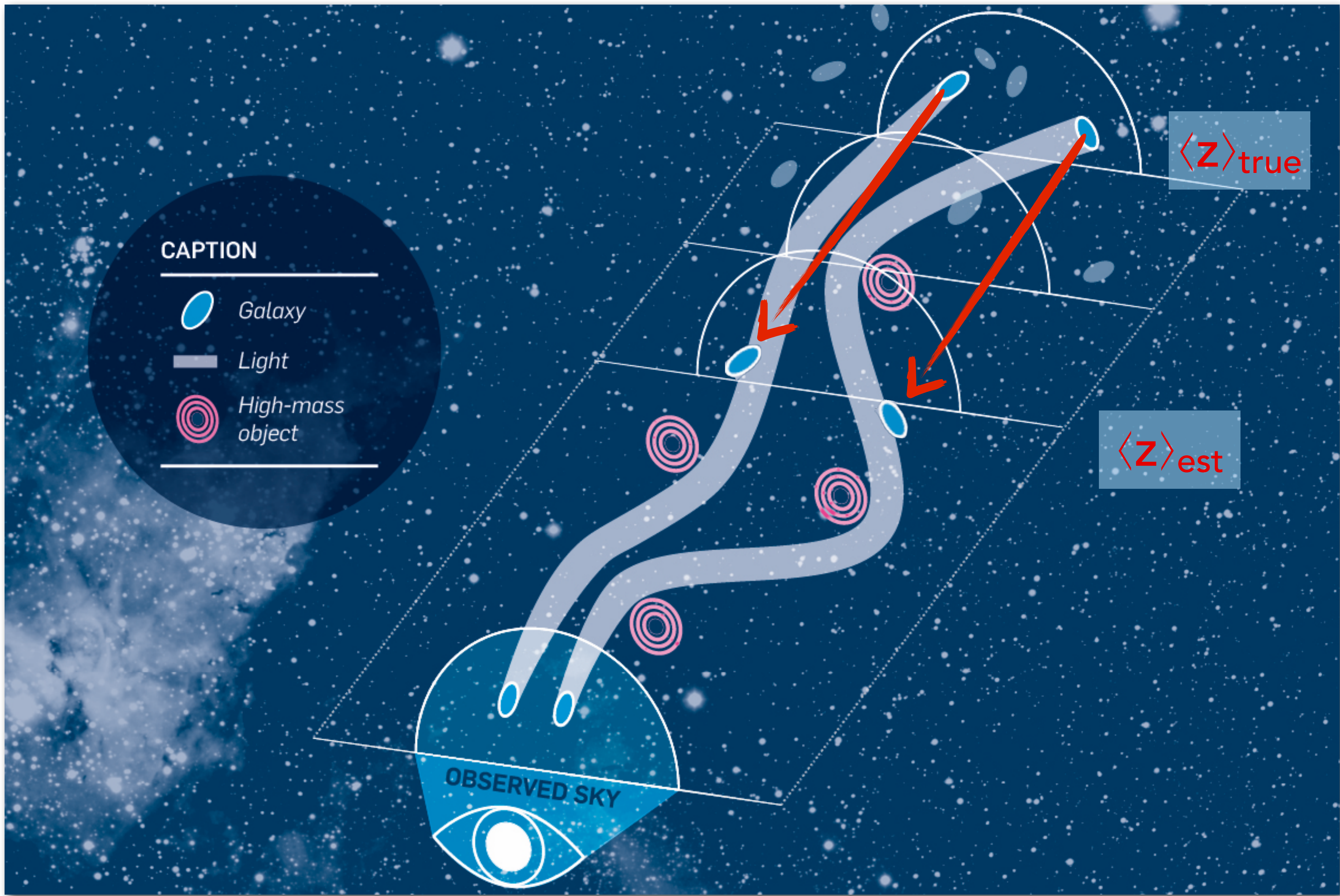




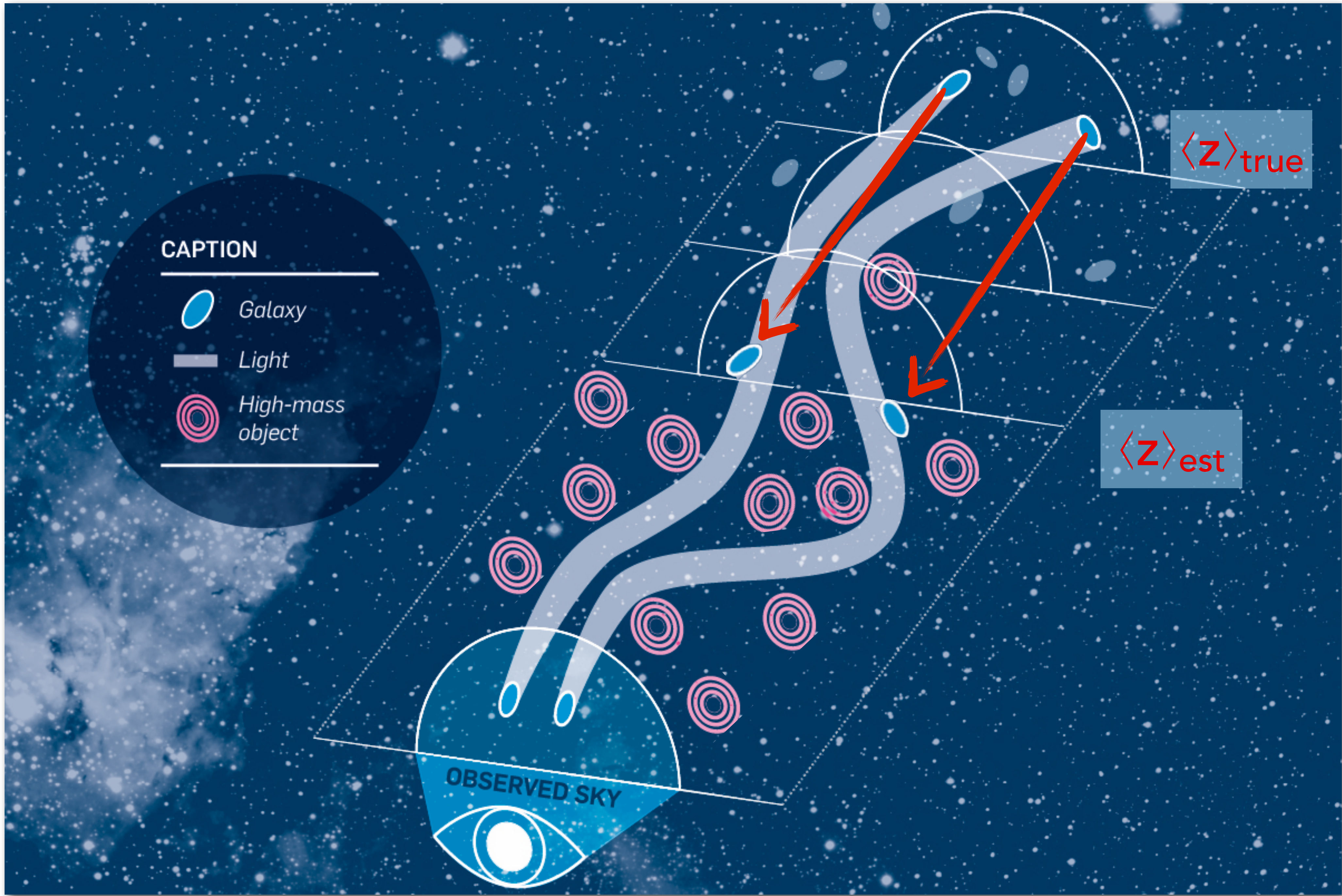














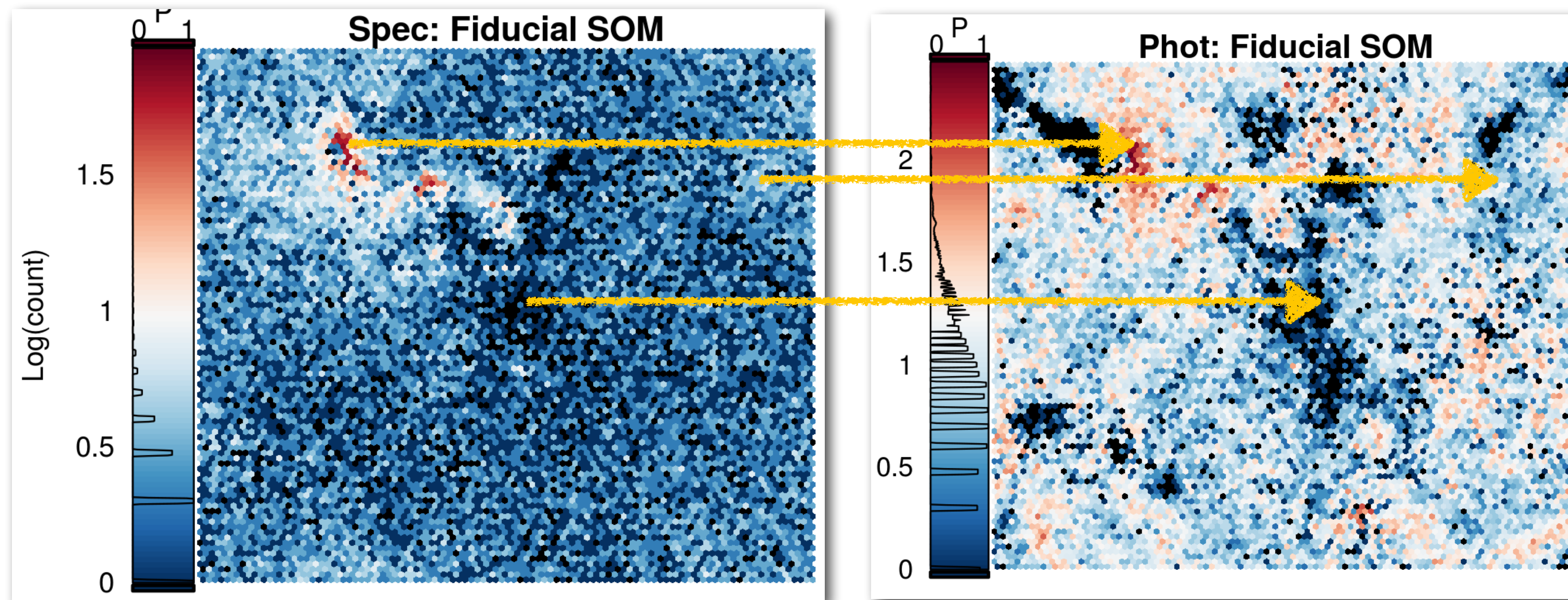
**How are redshift distributions  
calculated?**



# SOM Redshift Distribution Calibration

Leverages unsupervised machine learning to map two samples together:

1. Spectroscopic “calibration sources” with known redshift, to
2. Wide-field “photometric sources” with unknown redshift



KiDS-1000

Wright et al 2020a



# A ML classification problem

We use unsupervised machine learning to associate sources into cells  $c$ , and compute the target-sample redshift-distribution  $p_{\text{tg}}(z)$ :

$$\begin{aligned} p_{\text{tg}}(z) &= \sum_c p_{\text{tg}}(z | c) p_{\text{tg}}(c) \\ &\approx \sum_c p_{\text{tr}}(z | c) p_{\text{tg}}(c) \end{aligned}$$

The conditional probability of redshift given a cell (i.e. colour)

$p(z | c) = p(c | z)p(z)/p(c)$  is dependent on:

1. the likelihood of observing particular colours at a given redshift;
2. the “prior probability” of the sample as a function of redshift; and
3. the “covariate” probability distribution of the sample as a function of colour.

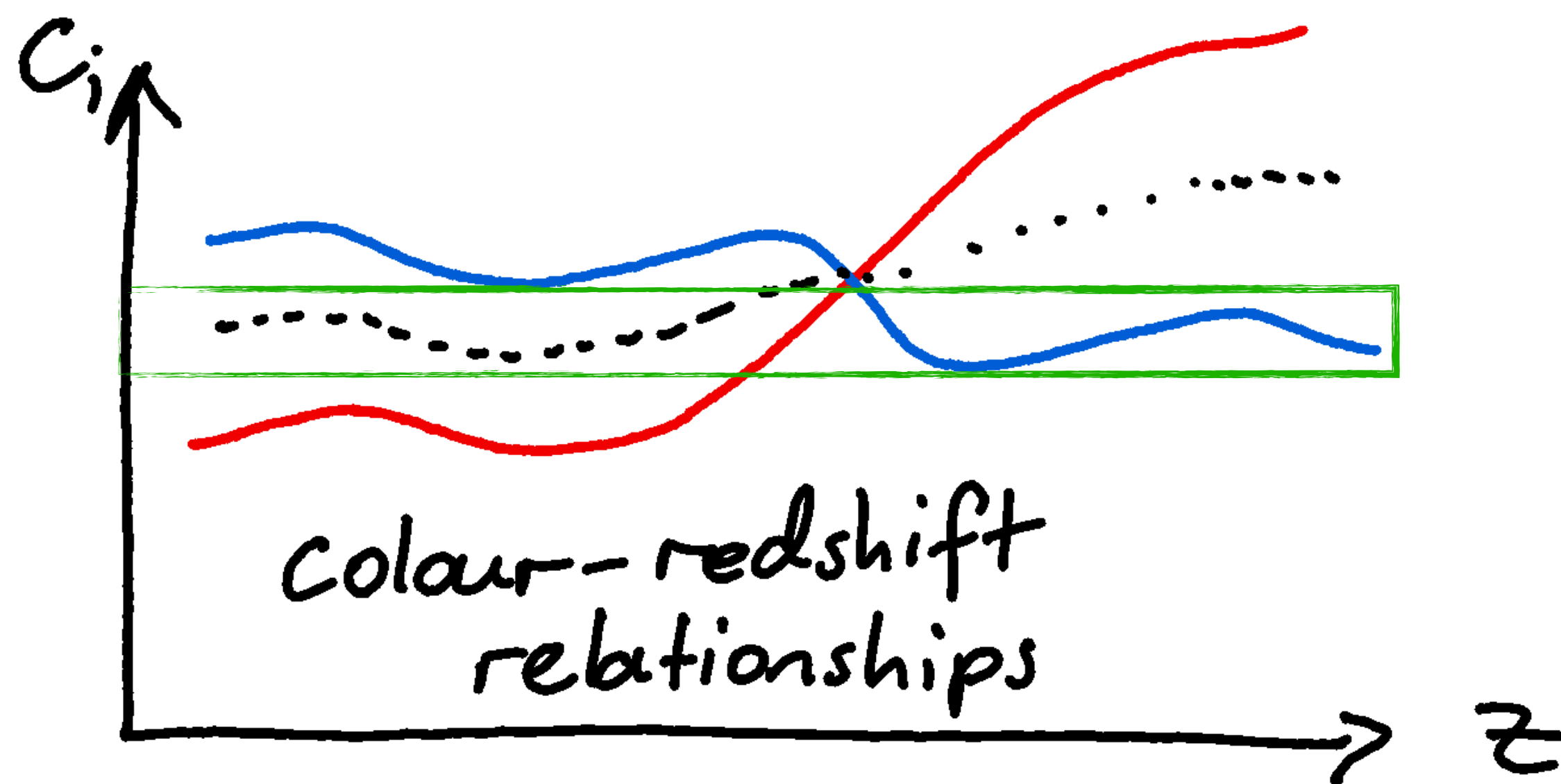


# Mapping between Colour and Redshift

Made possible because of the colour-redshift relation

$$P(z | c)$$

The probability of a source being at redshift  $z$  given its observed colours  $c$



“Red” galaxy SED

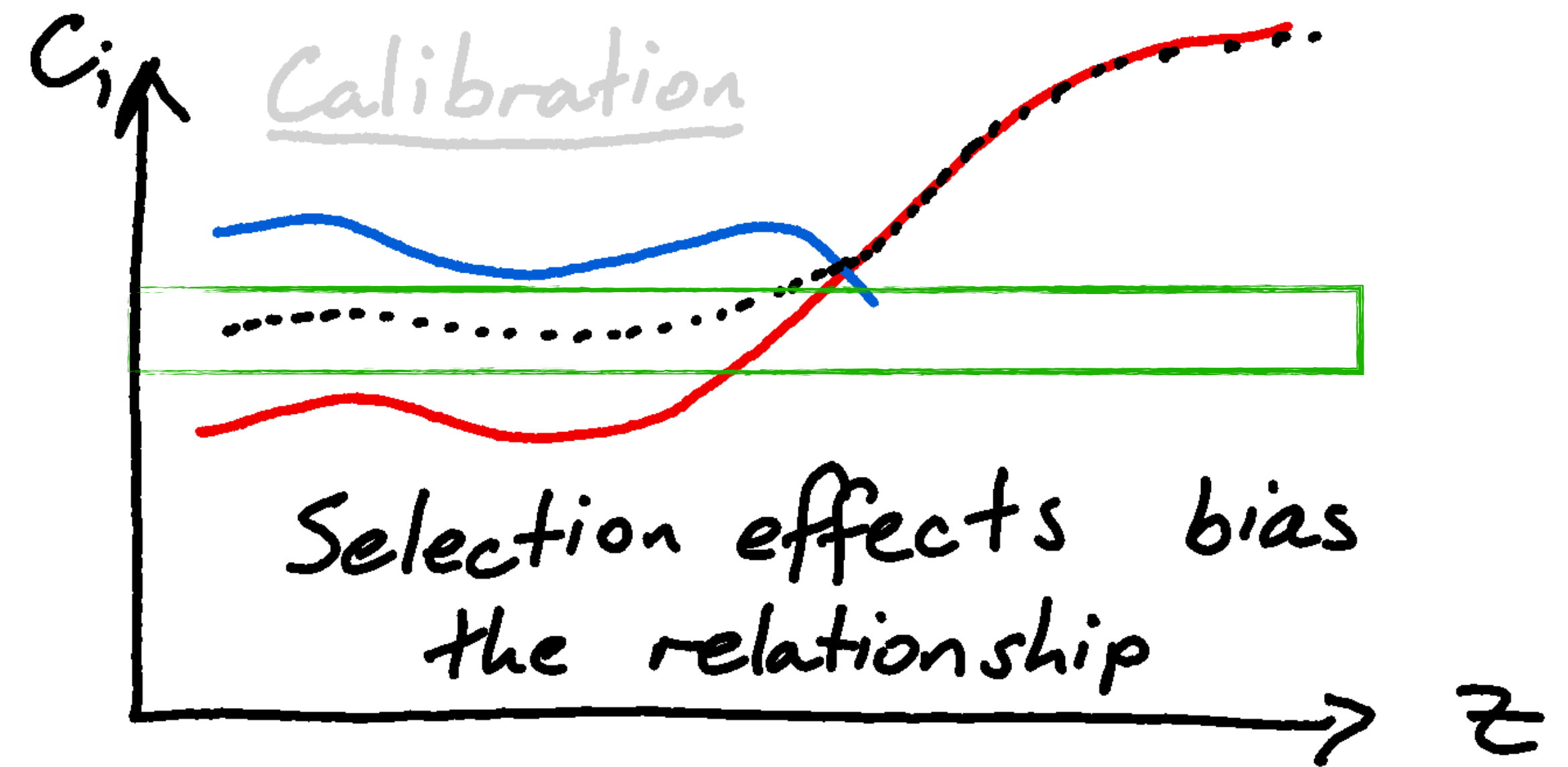
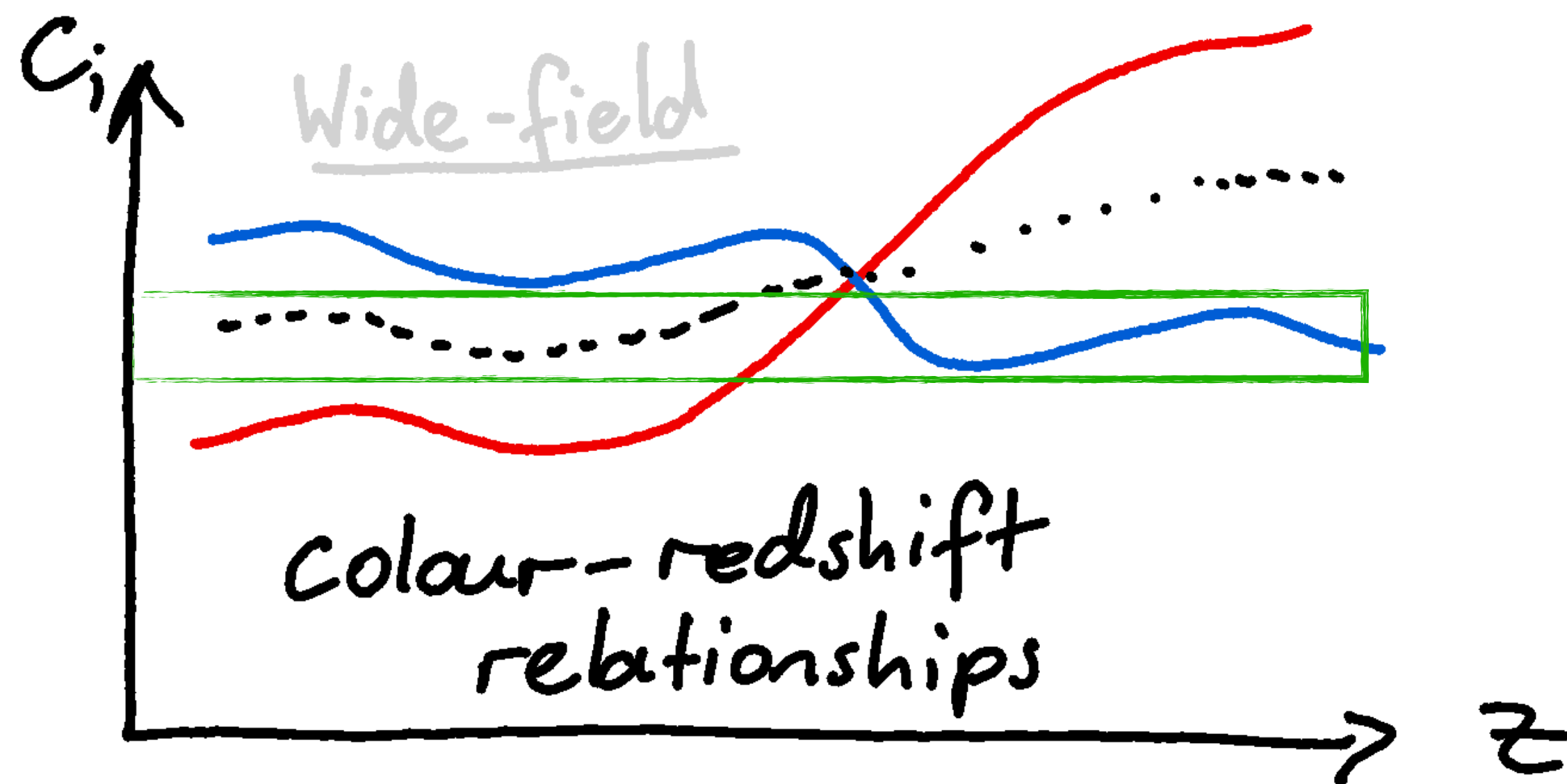
“Blue” galaxy SED

One colour cell



# The Problem: Covariate & Prior Probability Shift 11

Within a SOM cell, the distribution of redshift & colour differs between the calibration and wide-field samples



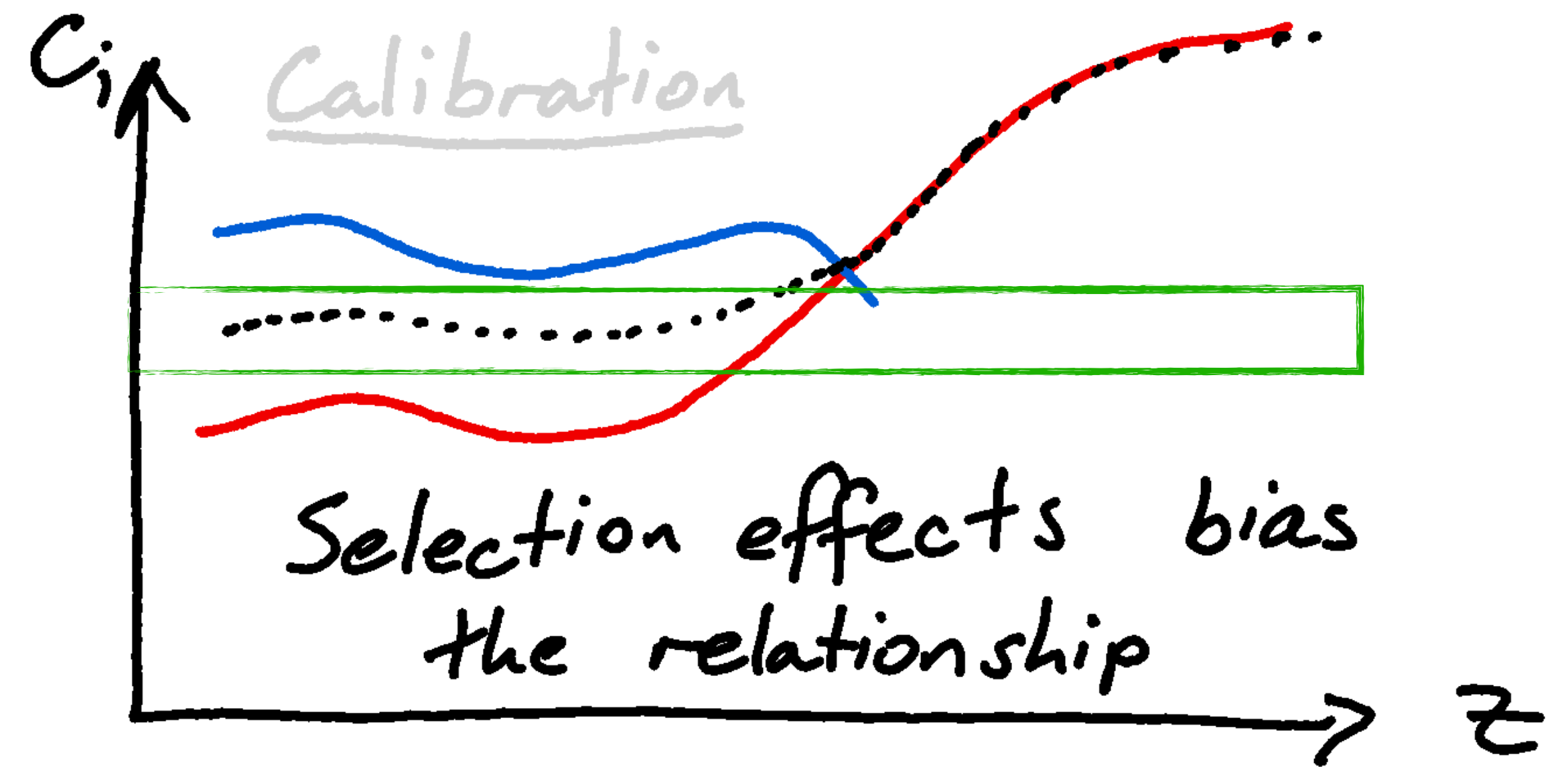
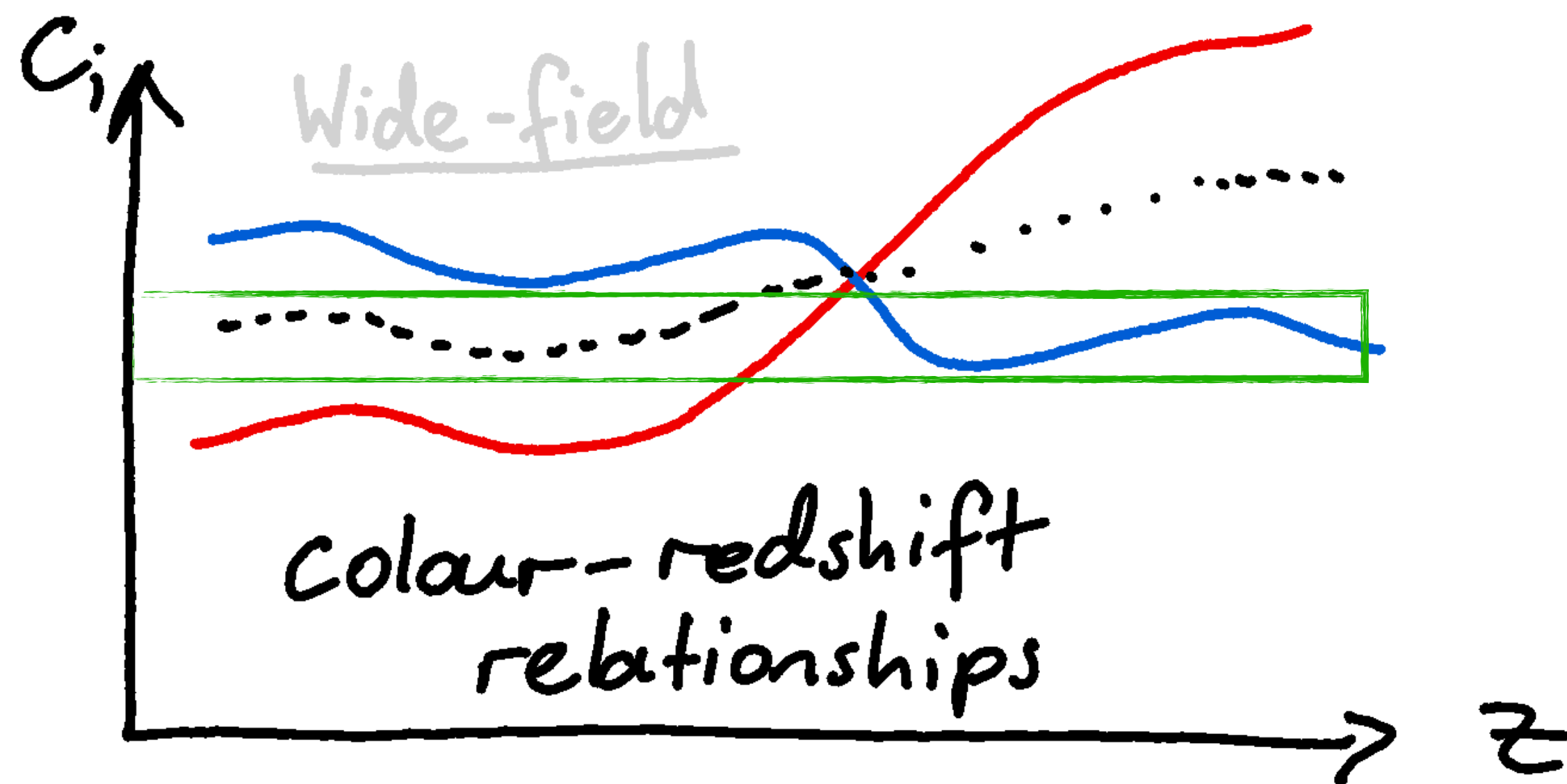


# The Problem: Covariate & Prior Probability Shift 11

Within a SOM cell, the distribution of redshift & colour differs between the calibration and wide-field samples

$$P_t(z) \neq P_v(z)$$

The overall distribution of redshift differs between the samples, so the mapping at fixed colour becomes biased





# The Problem

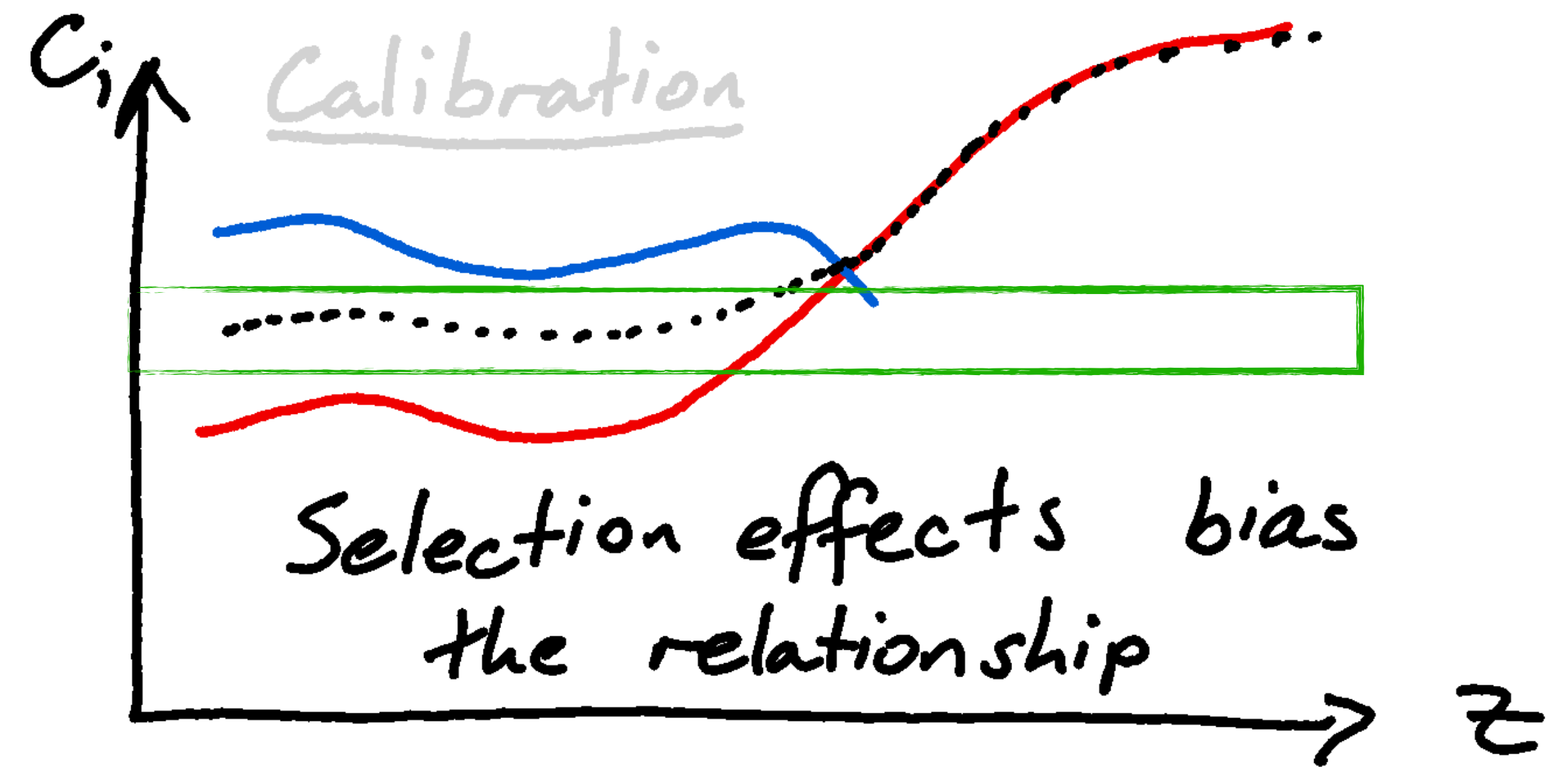
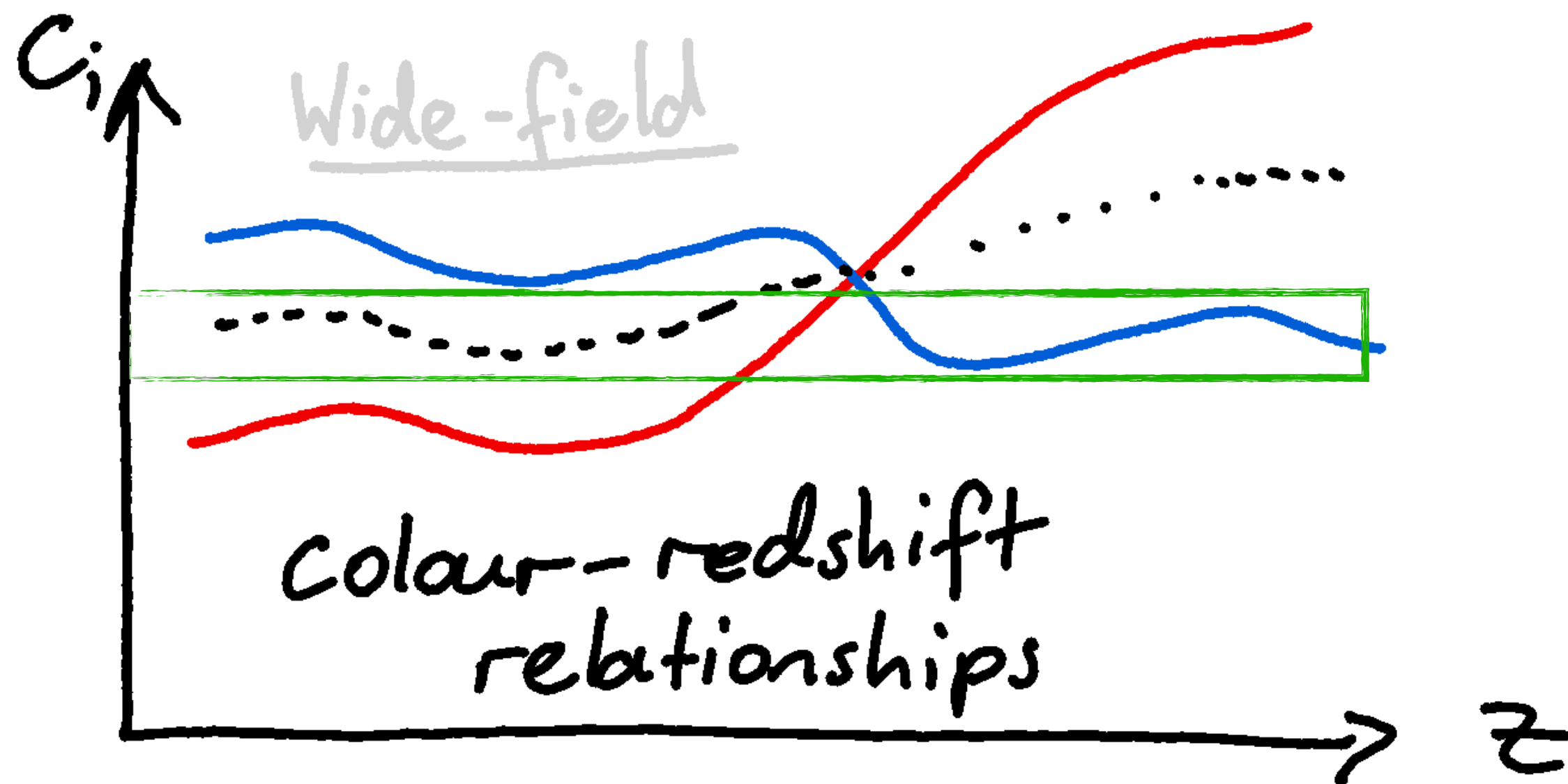
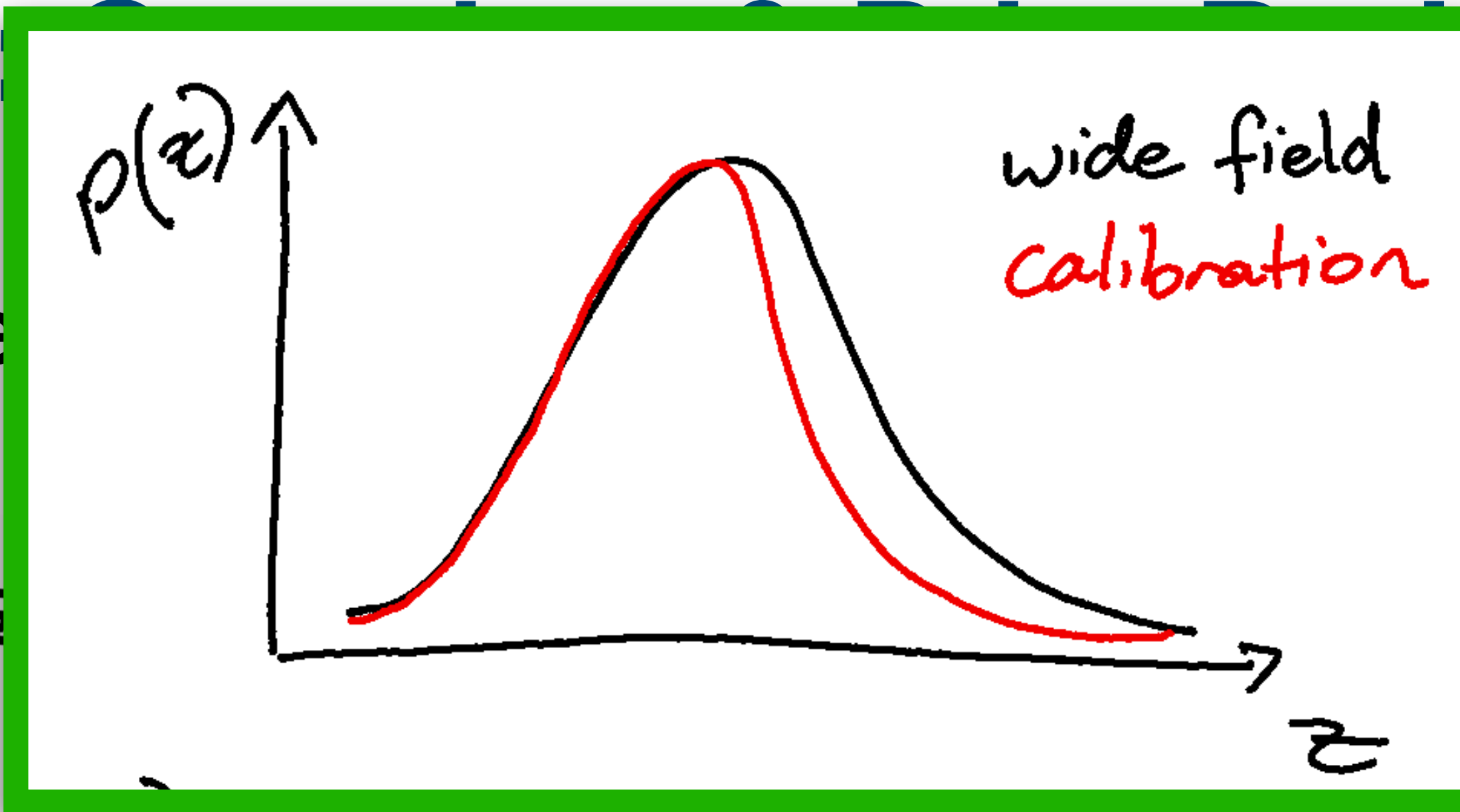
Within a SOM  
between

# Stability Shift 11

& colour differs  
samples

ft differs between the  
colour becomes biased

$$P_t(z) \neq P_v(z)$$





# So: essentially a ML classification problem <sup>12</sup>

There are three classic failure modes in ML regression/ classification problems:

1. Covariate shift:  $p_{\text{tr}}(z | c) = p_{\text{tg}}(z | c) \ \& \ p_{\text{tr}}(c) \neq p_{\text{tg}}(c)$
2. Prior Probability shift:  $p_{\text{tr}}(c | z) = p_{\text{tg}}(c | z) \ \& \ p_{\text{tr}}(z) \neq p_{\text{tg}}(z)$
3. Concept drift:  $p_{\text{tr}}(z | c) \neq p_{\text{tg}}(z | c)$

These all affect redshift calibration in various ways.

1. Targeting in spectroscopy differs from photometry
2. Redshift success and confidence is systematic
3. SOM cells have non-zero size  
➡ the above effects persist below the cell level

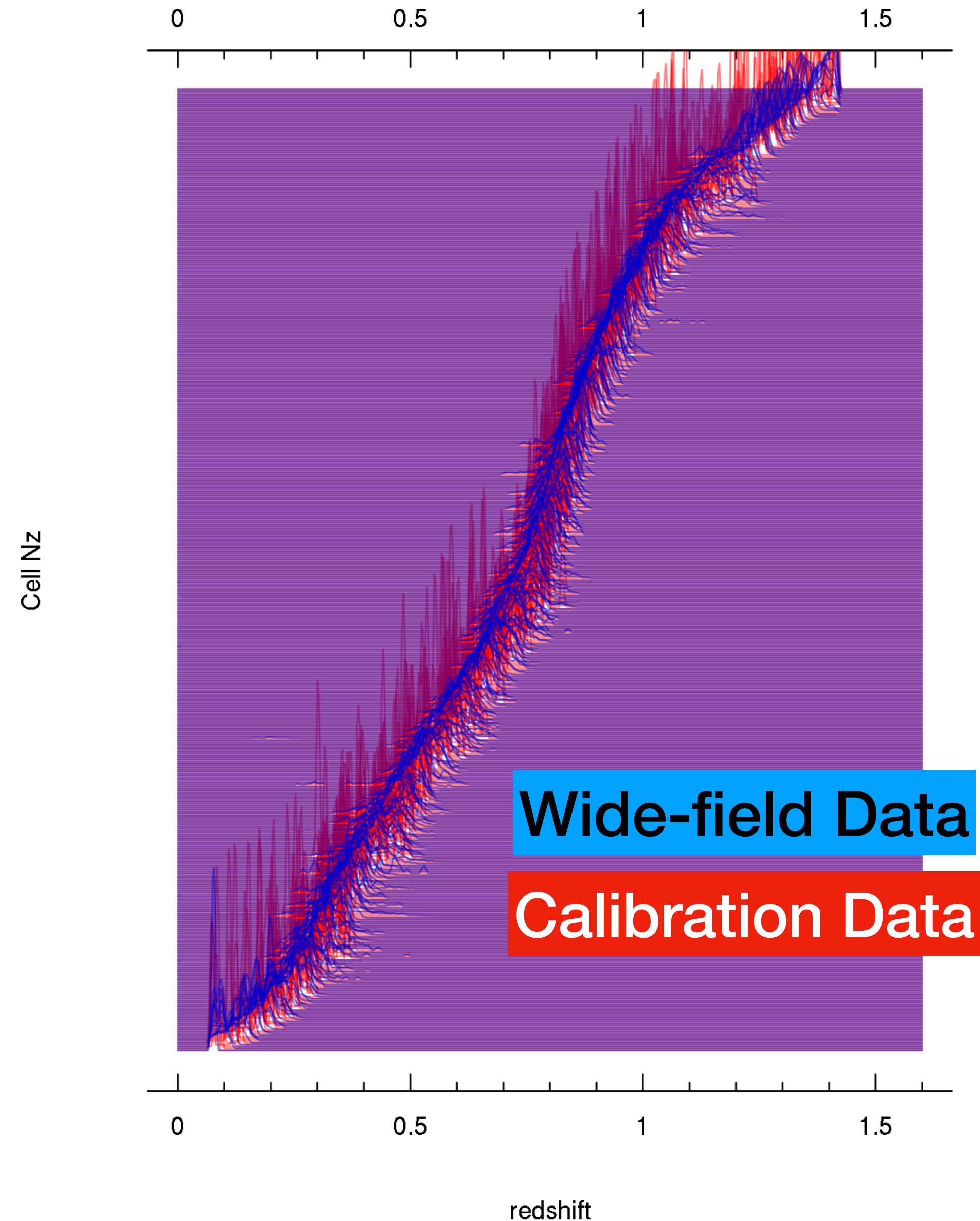


**Are our methods sufficient for  
Stage-IV (e.g. Euclid)?**



# No

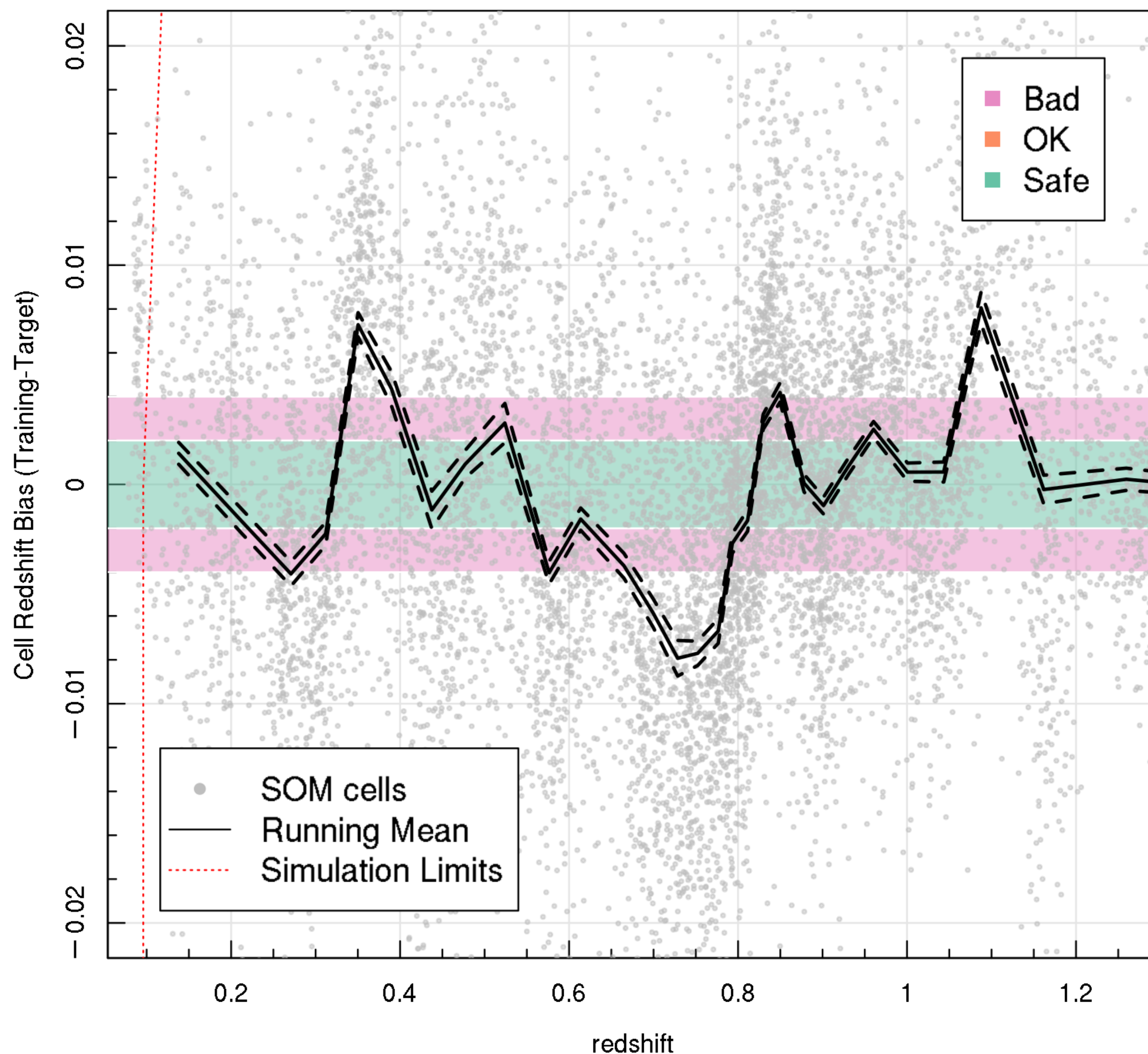
- Here I construct two simulated samples:
  1. A realistic spec-z calibration sample;
  2. A realistic wide-field shear sample
- And I **assume perfect photometry**
- Cells are **not delta-functions in redshift**:
  - Non-zero width allows selections at the within-cell level to play a role
  - Wider/more complex cells require more spectra to fairly sample the full  $N_z$
- Cells are not **sparse-sampled** by spectra:
  - spec-z targeting, success, confidence selections all contribute





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- Cells are not **sparse-sampled** by spectra:
  - spec-z targeting, success, confidence selections all contribute
- At the requirements of Euclid: these selection effects alone **exceed** the allowed error budget

Cell Bias for Realistic Calibration Samples (Model Photom)

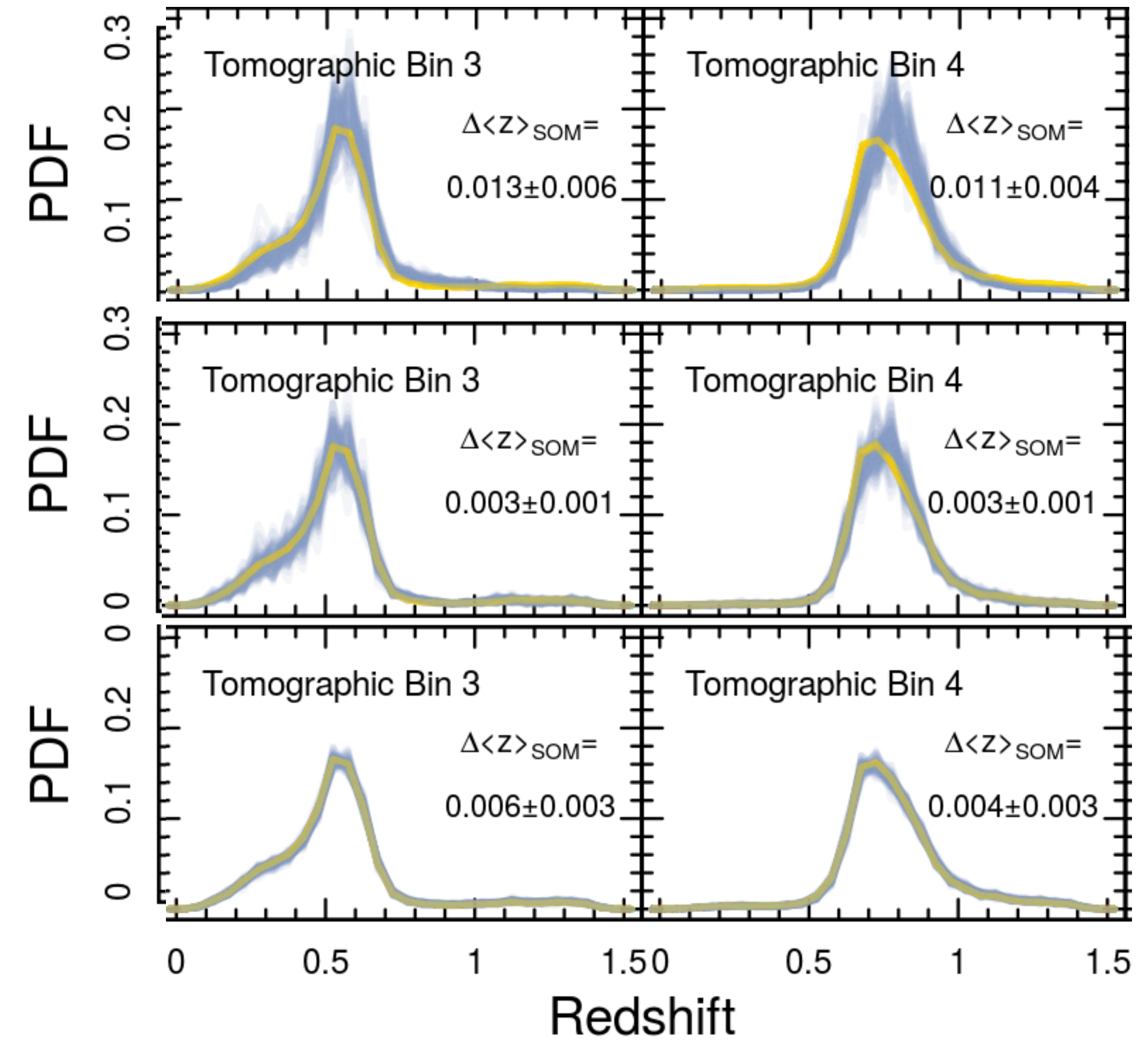
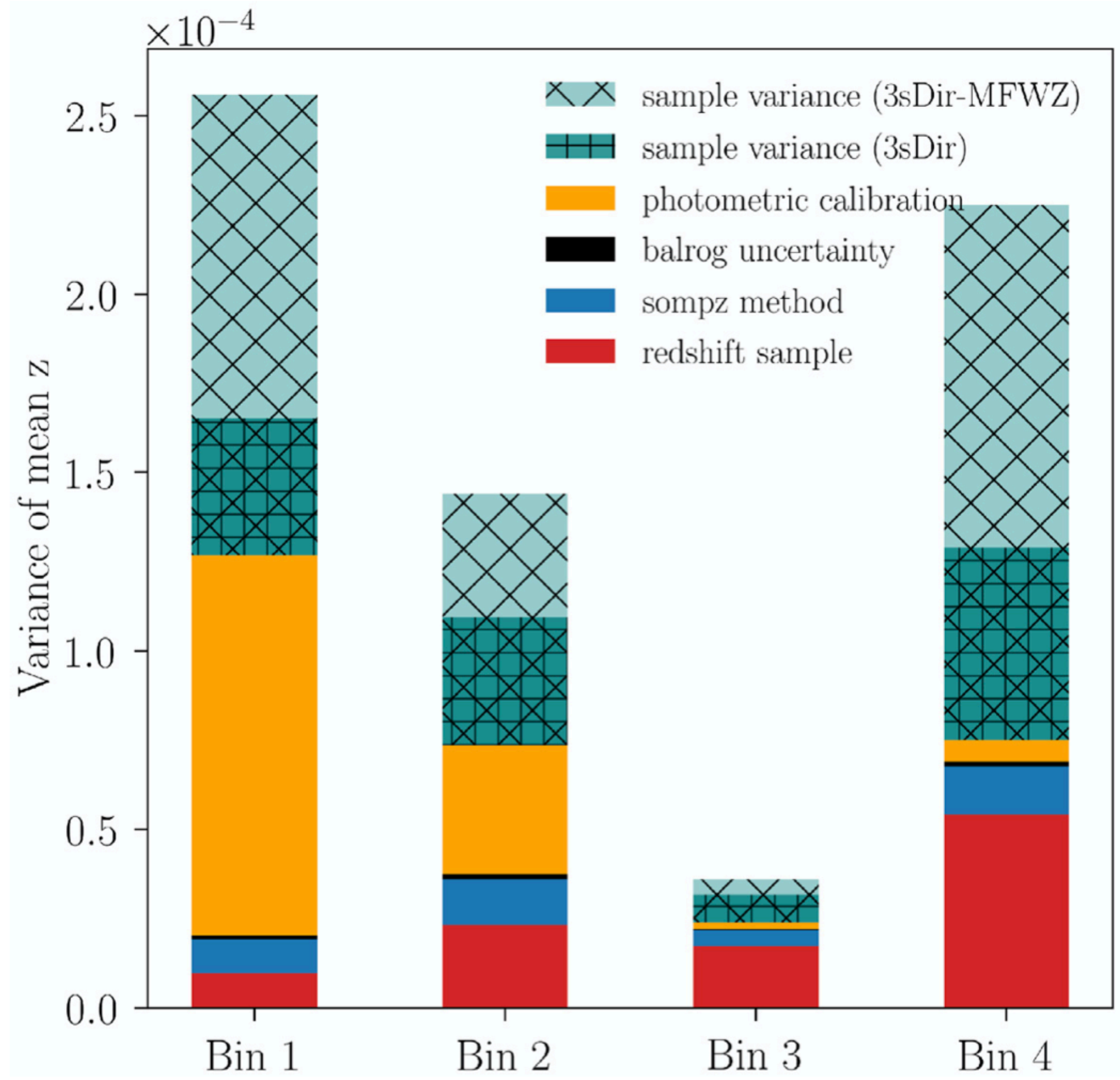




**What can we do?**

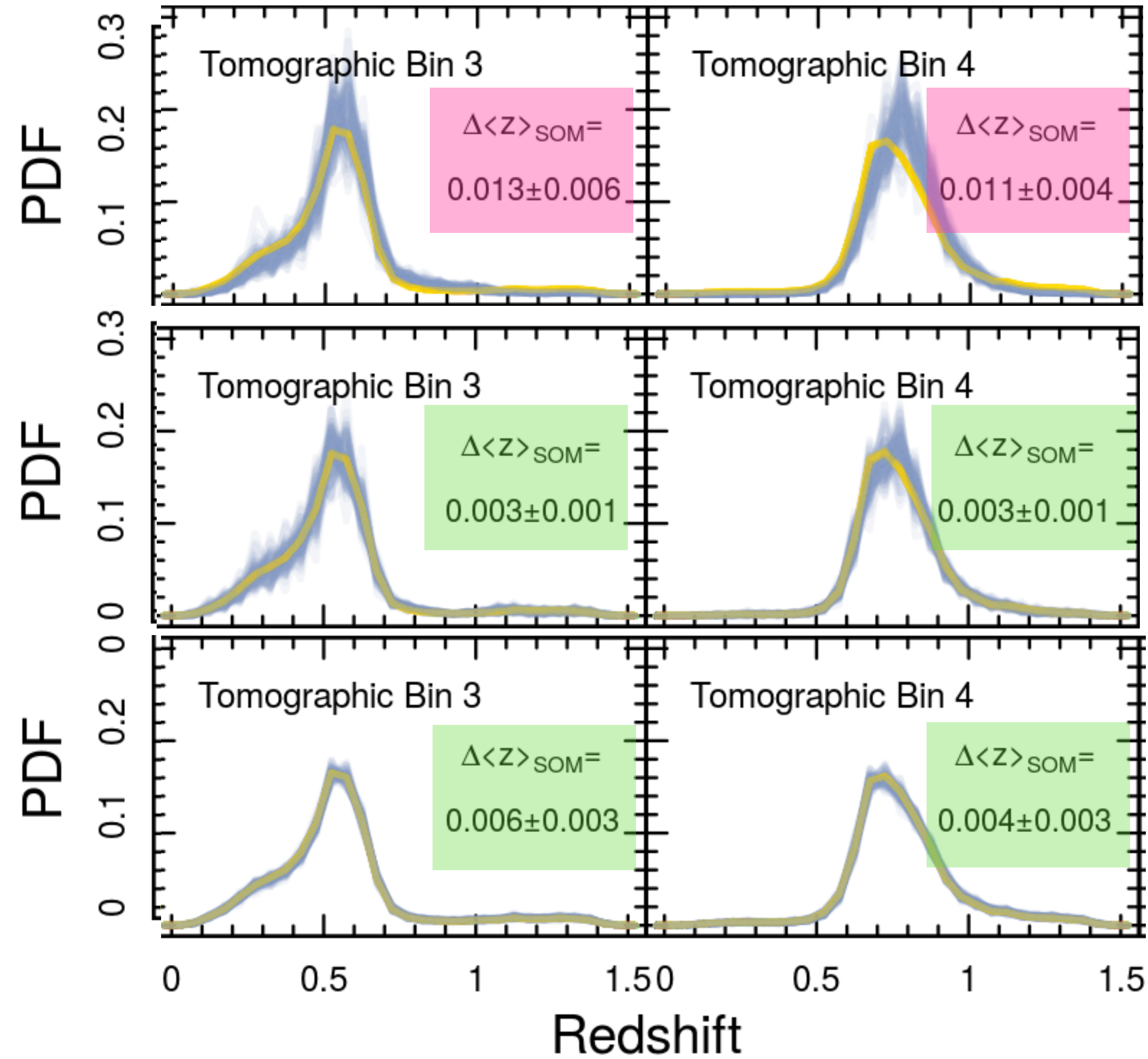
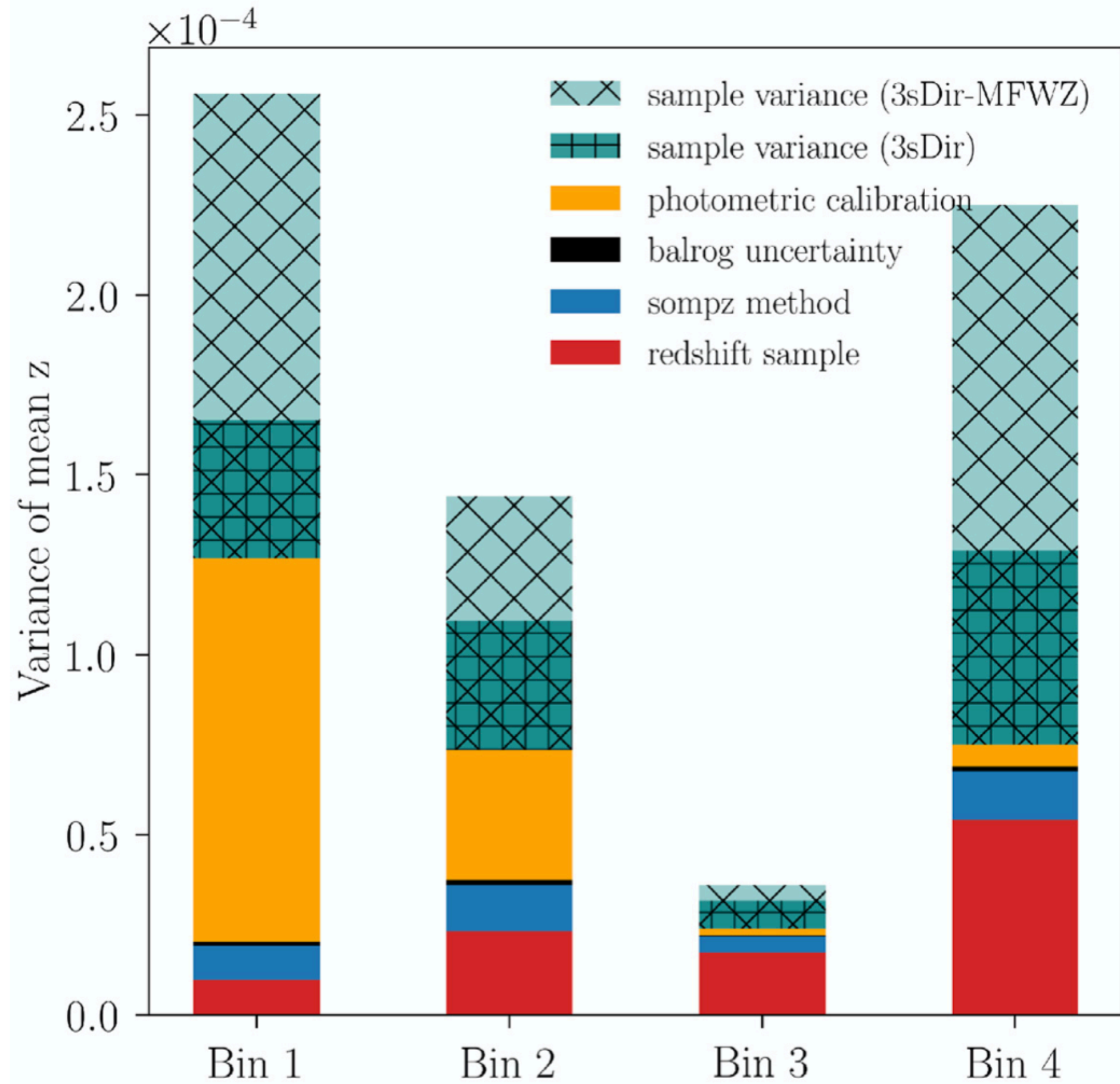


# Forward Modelling





# Forward Modelling



DES Y3  
Myles et al (2021)

One only sees these biases when you **jointly**  
simulate all expected systematic effects

KiDS-1000  
Wright et al 2020a

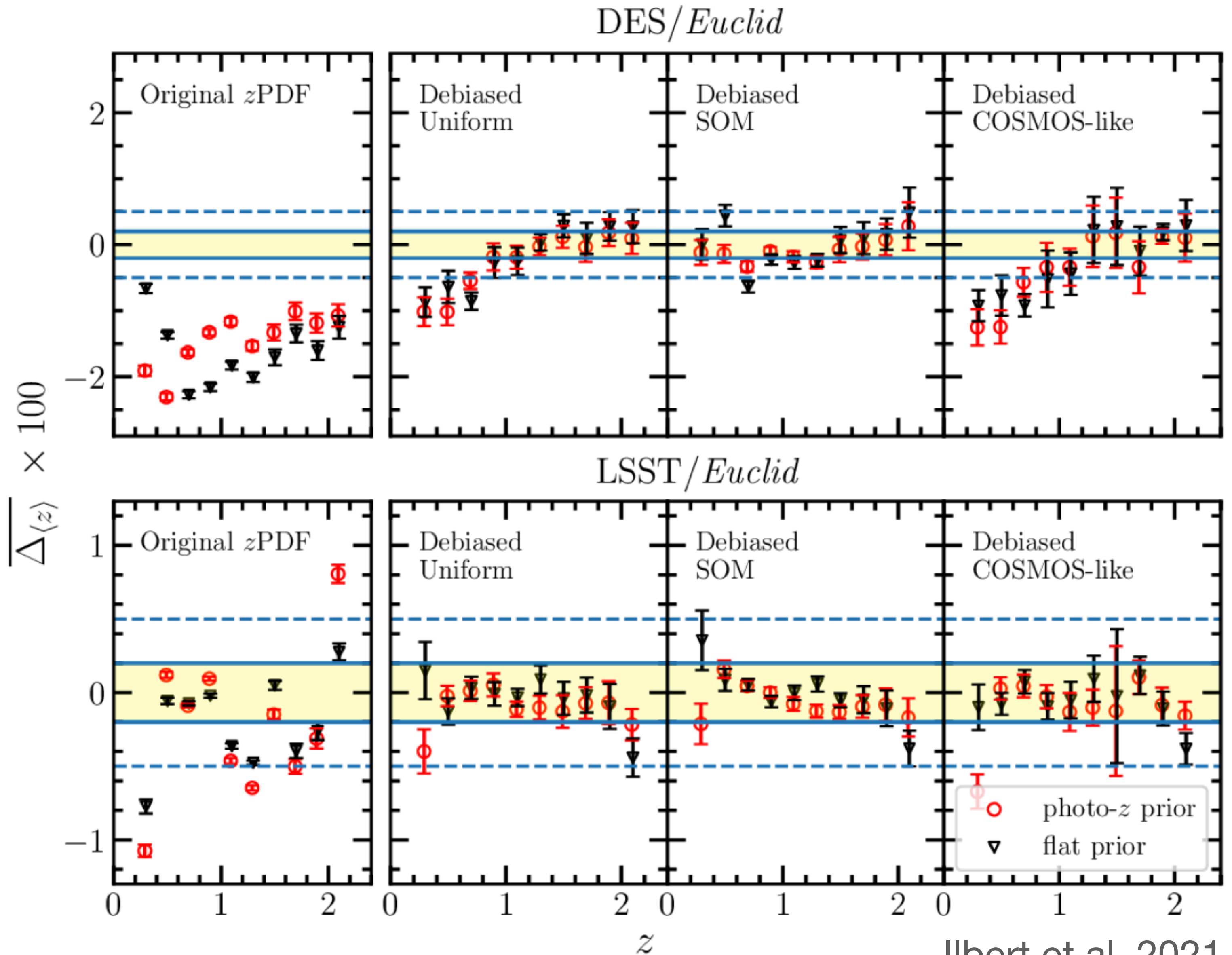


# Use population statistics to de-bias cells 17

Requires population statistics to be robust per cell (or group of cells).

Is more robust to failures of the calibration sample (which is good!)

Requires high-quality initial photo-z (DES not sufficient)

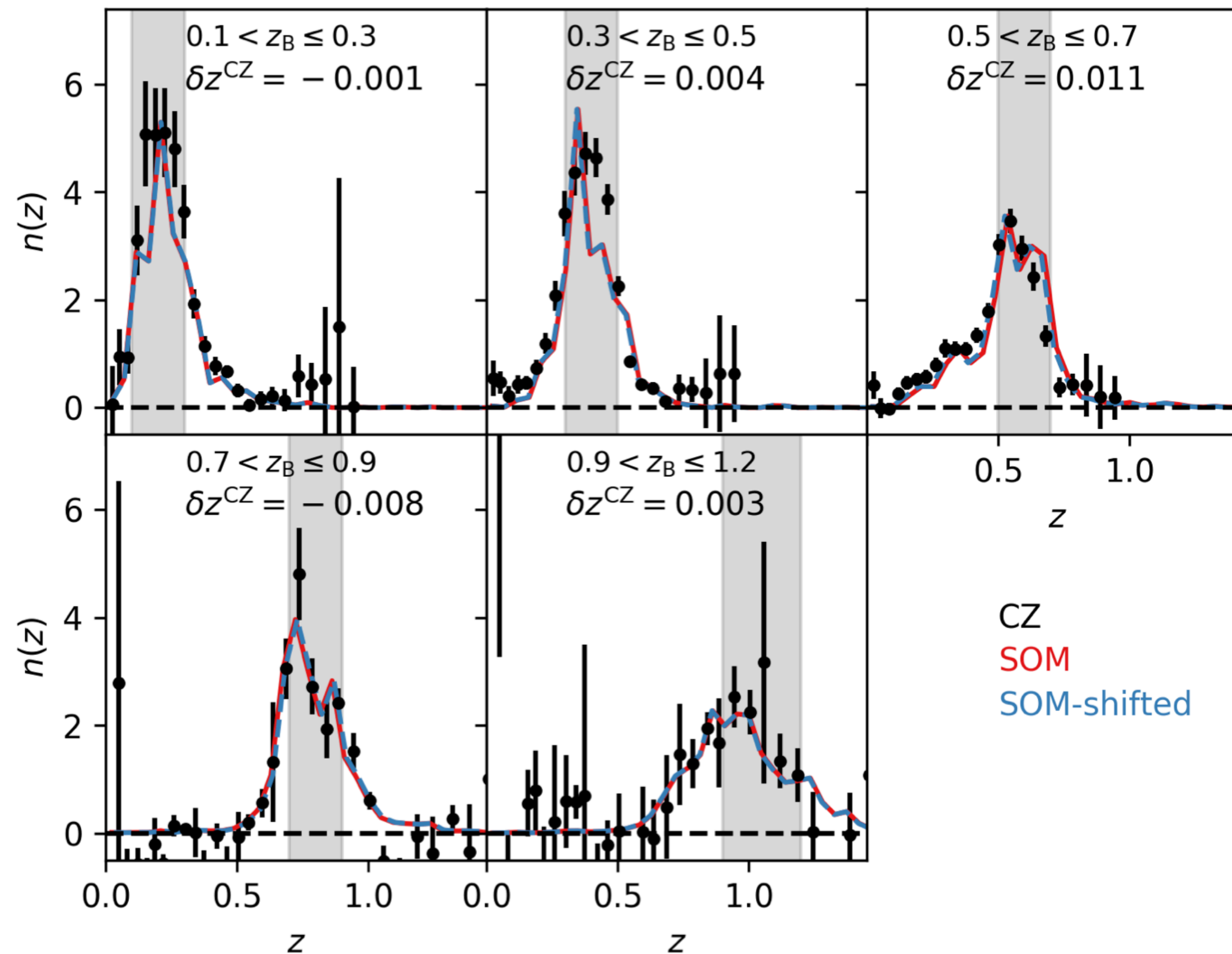




# Leverage multiple estimation techniques

## Clustering-based estimation methods have different selections

KiDS-1000



Uses the spatial cross correlation with a reference sample to produce  $Nz$

Reference sample is generic: need not be matched to the colour/magnitude range of the target sample

Marginalisation over evolution of galaxy bias is a complication



# Summary

- Cosmic shear is a valuable tool for exploring the matter power spectrum
- Machine learning estimation of source redshift distributions is a valuable tool
- But sampling and selection biases in spec-z samples lead to significant covariate shift within individual SOM cells.
- For Stage-III surveys, mitigation methods are currently suitable.
- For Stage-IV surveys like Euclid, they are not.
- Accurate cosmology with Euclid will require development of more comprehensive methods, such as combined clustering and colour-based approaches.

